

Dr. Kody Powell, University of Utah  
 Fundamentals of Smart Systems Ch En 5960 / 6960  
 Video and Reading Schedule

Assignment	Video/Reading Title	Where to Find It
Assignment 1: Dynamic modeling of a CSTR	Introduction to Process Modeling	<a href="https://www.youtube.com/watch?v=7wJkTgTsHw">https://www.youtube.com/watch?v=7wJkTgTsHw</a>
	Development of a simple dynamic gravity-drained tank model	<a href="https://www.youtube.com/watch?v=hf8xE1SEY-s">https://www.youtube.com/watch?v=hf8xE1SEY-s</a>
	Implementing a simple, dynamic gravity-drained tank model in Simulink	<a href="https://www.youtube.com/watch?v=epRgqDKFZVs">https://www.youtube.com/watch?v=epRgqDKFZVs</a>
	Dynamic Model of an Isothermal CSTR	<a href="https://www.youtube.com/watch?v=2g3XSc5jzOQ">https://www.youtube.com/watch?v=2g3XSc5jzOQ</a>
	Dynamic Simulation of CSTR in Simulink	<a href="https://www.youtube.com/watch?v=C6z4UisMjZY">https://www.youtube.com/watch?v=C6z4UisMjZY</a>
Assignment 2: Developing an automation scheme for a plant	Solving a first-order lag equation in Simulink	<a href="https://www.youtube.com/watch?v=eSyKReXmBuw">https://www.youtube.com/watch?v=eSyKReXmBuw</a>
	Modeling a linear valve with first order dynamics	<a href="https://www.youtube.com/watch?v=KgEbG3h4uv4">https://www.youtube.com/watch?v=KgEbG3h4uv4</a>
	Introduction to the concept of proportional and integral control	<a href="https://www.youtube.com/watch?v=1iwSYBjoBHW">https://www.youtube.com/watch?v=1iwSYBjoBHW</a>
	Controller tuning and controller saturation/windup	<a href="https://www.youtube.com/watch?v=hQoOMyNqFDU">https://www.youtube.com/watch?v=hQoOMyNqFDU</a>
	Creating a subsystem in Simulink	<a href="https://www.youtube.com/watch?v=FwqWv0DbQWM">https://www.youtube.com/watch?v=FwqWv0DbQWM</a>
	Introduction to cascade control	<a href="https://www.youtube.com/watch?v=HZgO6SLH2bk">https://www.youtube.com/watch?v=HZgO6SLH2bk</a>
	Introduction to override control	<a href="https://www.youtube.com/watch?v=gpZudY6TH78">https://www.youtube.com/watch?v=gpZudY6TH78</a>
	Override control and custom logic	<a href="https://www.youtube.com/watch?v=HQ6YtMq4wes">https://www.youtube.com/watch?v=HQ6YtMq4wes</a>
	Static Feedforward controller (optional)	<a href="https://www.youtube.com/watch?v=i8kYi1NQIVQ">https://www.youtube.com/watch?v=i8kYi1NQIVQ</a>

	Feedforward control example (optional)	<a href="https://www.youtube.com/watch?v=Ba6EyCYSEYM">https://www.youtube.com/watch?v=Ba6EyCYSEYM</a>
<b>Assignment 3: Developing a batch control sequence for product tanks</b>	How to program an on/off controller and use custom logic to implement hysteresis	<a href="https://www.youtube.com/watch?v=CrRq4GKENr8">https://www.youtube.com/watch?v=CrRq4GKENr8</a>
<b>Assignment 4: Empirical Modeling using Multiple Least Squares</b>	Mathematical derivation of multiple least squares	<a href="https://www.youtube.com/watch?v=oLwLFdy8sv4">https://www.youtube.com/watch?v=oLwLFdy8sv4</a>
	Application of multiple least squares in Matlab	<a href="https://www.youtube.com/watch?v=-Hh50-KGvIY">https://www.youtube.com/watch?v=-Hh50-KGvIY</a>
	How to export data from Simulink to Matlab	<a href="https://www.youtube.com/watch?v=mCJNuH5PdoU">https://www.youtube.com/watch?v=mCJNuH5PdoU</a>
	Mathematical derivation of least squares	<a href="https://isites.harvard.edu/fs/docs/icb.topic515975.files/OLSDerivation.pdf">https://isites.harvard.edu/fs/docs/icb.topic515975.files/OLSDerivation.pdf</a>
<b>Assignment 5: Quadratic Programming (QP) and Real-Time Optimization (RTO)</b>	Introduction to Optimization	<a href="https://www.youtube.com/watch?v=11JqGiG_P_w">https://www.youtube.com/watch?v=11JqGiG_P_w</a>
	Overview of Quadratic Programming	<a href="https://www.youtube.com/watch?v=GZb9647X8sg">https://www.youtube.com/watch?v=GZb9647X8sg</a>
	How to solve a Quadratic Program in Matlab	<a href="https://www.youtube.com/watch?v=2LbNIDwla_c">https://www.youtube.com/watch?v=2LbNIDwla_c</a>
	Overview of Real-Time Optimization	Placeholder for next year
<b>Assignment 6: Nonlinear Programming (NLP) and RTO</b>	Overview of Nonlinear Programming	<a href="https://www.youtube.com/watch?v=K7eHfL4dYN8">https://www.youtube.com/watch?v=K7eHfL4dYN8</a>
	Application of Nonlinear Programming in Matlab	<a href="https://www.youtube.com/watch?v=qTJDNXRfcsc">https://www.youtube.com/watch?v=qTJDNXRfcsc</a>

<b>Assignment 7: Machine Learning Using Artificial Neural Networks</b>	Overview of Artificial Neural Networks (ANNs)	<a href="https://www.youtube.com/watch?v=v2tKoymKluE">https://www.youtube.com/watch?v=v2tKoymKluE</a>
	Application of Artificial Neural Networks Using Matlab	<a href="https://www.youtube.com/watch?v=DCaSedfnMbk">https://www.youtube.com/watch?v=DCaSedfnMbk</a>