Example 1. Linearization with one variable

Linearize the following equation around $\overline{x} = 3$:

$$f(x) = 3x^3 + 5x^2 + 27$$

- (i) Write the Taylor's series expansion: f(x) =
- (ii) Evaluate $f(\bar{x}) =$

(iii) What is the derivative of the function?
$$\left(\frac{df}{dx}\right) =$$

- (iv) Evaluate $f'(\bar{x}) =$
- (v) Write the final linear expression f(x) =

Example 2. Linearization with two variables

Linearize the following equation around $\overline{x} = 2$ and $\overline{y} = 2$:

$$f(x, y) = 3xy + y^2 - 3x^2$$

(i) Write the Taylor's series expansion: f(x,y) =

(ii) Evaluate
$$f(\overline{x}, \overline{y}) =$$

(iii) What are the partial derivatives of the function?

$$\frac{\partial f}{\partial x} = \frac{\partial f}{\partial y} =$$

(iv) Evaluate
$$\frac{\partial f}{\partial x}\Big|_{\bar{x},\bar{y}} = \frac{\partial f}{\partial x}\Big|_{\bar{x},\bar{y}}$$

$$\frac{|y|}{\partial y}\Big|_{\overline{x},\overline{y}} =$$

(v) Write the final linear expression: f(x) =



 $-r_{A} = k_{1}C_{A}^{2} - k_{2}C_{A}C_{B}$

(i) Write the transient mole balance for species A:

$$V \frac{dC_A}{dt} =$$

- (ii) Assume k₁, k₂, q_i, q, and V are constant. The function to linearize is just the RHS of the above equation! The variables are ____, ____, and ____.
- (iii) At steady state, what is the value of $V \frac{dC_A}{dt}$? _____. Therefore, $f(\overline{C}_{A,i}, \overline{C}_A, \overline{C}_B) =$ _____.
- (iv) Write the Taylor's series expansion: $f(C_{A,i}, C_A, C_B) =$
- (v) What are the partial derivatives of the function?

$$\frac{\partial f}{\partial C_{A,i}} = \frac{\partial f}{\partial C_A} = \frac{\partial f}{\partial C_B} = \frac{\partial f}{\partial C_B}$$

(vi) Evaluate $\left. \frac{\partial f}{\partial C_{A,i}} \right|_{ss} =$ $\left. \frac{\partial f}{\partial C_A} \right|_{ss} =$ $\left. \frac{\partial f}{\partial C_B} \right|_{ss} =$

(vii) Write the final linear expression:

$$f(C_{A,i}, C_A, C_B) = \underline{\qquad} + \underline{\qquad} (C_{A,i} - \overline{C}_{A,i}) + \underline{\qquad} (C_A - \overline{C}_A) + \underline{\qquad} (C_B - \overline{C}_B)$$

(viii) Now introduce deviation variables (the prime here is <u>not</u> a derivative):

$$C'_{A,i} = C_{A,i} - \overline{C}_{A,i}$$
$$C'_{A} = C_{A} - \overline{C}_{A}$$
$$C'_{B} = C_{B} - \overline{C}_{B}$$

(ix) The transient linearized equation now becomes:

$$V\frac{dC_A}{dt} = V\frac{dC'_A}{dt} = \underline{\qquad} C'_{A,i} + \underline{\qquad} C'_A + \underline{\qquad} C'_B$$

(x) All of the underlined terms above are constants, since they were evaluated at the steady-state condition. For convenience in this equation, call the second constant c_1 . The standard form for solving this equation using Laplace transforms is:

$$\tau \frac{dy'}{dt} + y' = f(x_1, x_2, x_3, etc.)$$

Put the equation in (ix) into standard form:

$$\frac{V}{c_1}\frac{dC'_A}{dt} + C'_A = \underline{\qquad} C'_{A,i} + \underline{\qquad} C'_B$$